Visualizing Projection Algorithms with Application to Protein Reconstruction

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ILELI Challenges in 21st Century Experimental Mathematical Computation 21st-25th July 2014 at Brown University

Projection methods are a family of iterative algorithms useful for solving the feasibility problem which asks:

find $x \in C_1 \cap C_2 \subseteq \mathcal{H}$,

where C_1 and C_2 are constraint sets in a Hilbert space \mathcal{H} .

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- When one or more of the constraint sets are non-convex, theory is largely unknown. However, one particular projection method, the Douglas-Rachford method, has been (experimentally) observed to successfully solve a large range of non-convex problems.

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- When one or more of the constraint sets are non-convex, theory is largely unknown. However, one particular projection method, the Douglas-Rachford method, has been (experimentally) observed to successfully solve a large range of non-convex problems. Examples:
 - Solving Sudoku and nonogram puzzles, 8-queens and generalizations, enumerating Hadamard matrices, phase retrieval & ptychography, ...

The focus of this talk is application of the Douglas–Rachford method as a heuristic for non-convex feasibility problems guided by convex theory.

Let $S \subseteq \mathcal{H}$. The (nearest point) projection onto S is the (set-valued) mapping,

 $P_{S}x := \arg\min_{s \in S} \|s - x\|.$

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$$x_{n+1} = T_{C_1, C_2} x_n$$
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• First studied by Douglas & Rachford (1956) in connection with heat conduction problems, and later by Lions & Mercier (1979) for finding a zero in the sum of two maximal monotone operators.

Theorem (Basic behaviour of the Douglas–Rachford method)

Suppose C_1 , C_2 are closed convex subsets of a finite dimensional Hilbert space \mathcal{H} . For any $x_0 \in \mathcal{H}$, define $x_{n+1} = T_{C_1, C_2} x_n$. If $C_1 \cap C_2 \neq \emptyset$, then $x_n \to x$ such that $P_{C_1} x \in C_1 \cap C_2$. If $C_1 \cap C_2 = \emptyset$, then $||x_n|| \to +\infty$.

It is important to monitor the shadow sequence (P_{C1}x_n)[∞]_{n=1}, not just the iterates (x_n)[∞]_{n=1}.

Scinderella: Interactive Geometry



http://carma.newcastle.edu.au/jon/reflection.html

Matthew K. Tam (University of Newcastle) Visualizing Projection Algorithms

Proteins are large biomolecules comprising of multiple amino acid chains.



They participate in virtually every cellular process, and knowledge of structural conformation gives insights into the mechanisms by which they perform.

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We say $D = (D_{ij}) \in \mathbb{R}^{m \times m}$ is a Euclidean distance matrix (EDM) if there exists points $p_1, \ldots, p_m \in \mathbb{R}^q$ such that

$$D_{ij} = \|p_i - p_j\|^2.$$

When this holds for points in \mathbb{R}^{q} , we say that D is embeddable in \mathbb{R}^{q} .

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We formulate protein reconstruction as a matrix completion problem:

Find a member from a given family of matrices, knowing only a subset of its entries.

Find a EDM, embeddable in \mathbb{R}^3 , knowing only short inter-atomic distances.

A Feasibility Problem Formulation

Denote by Q the Householder matrix defined by

$$Q := I - rac{2
u
u^T}{
u^T
u}$$
, where $u = \begin{bmatrix} 1, 1, \dots, 1, 1 + \sqrt{m} \end{bmatrix}^T \in \mathbb{R}^m$.

Theorem (Hayden–Wells 1988)

A nonnegative, symmetric, hollow matrix X, is a EDM iff $\hat{X} \in \mathbb{R}^{(m-1) \times (m-1)}$ in

$$Q(-X)Q = \begin{bmatrix} \hat{X} & d \\ d^T & \delta \end{bmatrix}$$
(*)

is positive semi-definite (PSD). In this case, X is embeddable in \mathbb{R}^q where $q = \operatorname{rank}(\widehat{X}) \leq m-1$ but not in \mathbb{R}^{q-1} .

Let *D* denote the partial EDM (obtained from NMR), and $\Omega \subset \mathbb{N} \times \mathbb{N}$ the set of indices for known entries. In light of the above characterization, the protein reconstruction problem is the feasibility problem with constraints:

$$C_1 = \{X \in \mathbb{R}^{m \times m} : X \ge 0, X_{ij} = D_{ij} \text{ for } (i, j) \in \Omega\},\$$

$$C_2 = \{X \in \mathbb{R}^{m \times m} : \widehat{X} \text{ in } (*) \text{ is PSD with } \operatorname{rank} \widehat{X} \le 3\}.$$

Recall the constraint sets:

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Now,

- C_1 is a convex set (intersection of cone and affine subspace).
- C_2 is convex iff $m \leq 2$ (in which case $C_2 = \mathbb{R}^{m \times m}$).

For interesting problems, C_2 is **never convex**.

Computing Projections and Reflections

Recall the constraint sets:

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The projection onto C_1 is given (point-wise) by

$$P_{C_1}(X)_{ij} = \begin{cases} D_{ij} & \text{if } (i,j) \in \Omega, \\ \max\{0, X_{ij}\} & \text{otherwise.} \end{cases}$$

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The projection onto C_2 is the set

 $P_{C_2}(X) = \left\{ -Q \begin{bmatrix} \widehat{Y} & d \\ d^T & \delta \end{bmatrix} Q : Q(-X)Q = \begin{bmatrix} \widehat{X} & d \\ d^T & \delta \end{bmatrix}, \quad \widehat{X} \in \mathbb{R}^{(m-1)\times(m-1)}, \quad \widehat{Y} \in P_S \widehat{X} \right\},$ where *S* is the set of PSD matrices of rank 3 or less.

• One method to compute P_S is using the eigen-decomposition of X.

Numerical and Visual Experiments

The reconstruction approach is as follows:



¹http://spdbv.vital-it.ch/

Experiment 1: We first examine if the Douglas–Rachford method able to solve the problem, and then investigate the proportion of distances required for a successful reconstruction.

- The protein 1PTQ, whose structure is known, was used.
- Attempt reconstruction using the Douglas–Rachford method from a partial EDM containing the smallest *p* percent of inter-atomic distances for *p* = 1, 2, ..., 15.
- 1,000 iterations performed starting from a random initialization (approx. 2min computation time per instance).



Actual conformation



Reconstructed conformation

Distances in partial EDM = 1%.



Actual conformation



Reconstructed conformation

Distances in partial EDM = 2%.



Actual conformation



Reconstructed conformation

Distances in partial EDM = 3%.



Actual conformation



Reconstructed conformation

Distances in partial EDM = 4%.



Actual conformation



Reconstructed conformation

Distances in partial EDM = 5%.



Actual conformation



Reconstructed conformation

Distances in partial EDM = 6%.



Actual conformation



Reconstructed conformation

Distances in partial EDM = 7%.



Actual conformation



Reconstructed conformation

Distances in partial EDM = 8%.



Actual conformation



Reconstructed conformation

Distances in partial EDM = 9%.



Actual conformation



Reconstructed conformation

Distances in partial EDM = 10%.



Actual conformation



Reconstructed conformation

Distances in partial EDM = 11%.



Actual conformation



Reconstructed conformation

Distances in partial EDM = 12%.



Actual conformation



Reconstructed conformation

Distances in partial EDM = 13%.



Actual conformation



Reconstructed conformation

Distances in partial EDM = 14%.



Actual conformation



Reconstructed conformation

Distances in partial EDM = 15%.



Figure : The reconstructions of 1PTQ. The top-left conformation was obtained from 1% of distances, and the bottom-right from 15% of distances.



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• Reconstruction seem possible. For 1,000 iterations approx. 10% of the total (non-zero) distances are needed.

Experiment 2: We consider the simplest realistic protein conformation determination problem.

NMR experiments were simulated for proteins with known conformation by computing the partial EDM containing all inter-atomic distances < 6Å.

Protein	# Atoms	# Residues	Known Distances
1PTQ	404	50	8.83%
1HOE	581	74	6.35%
1LFB	641	99	5.57%
1PHT	988	85	4.57%
1POA	1067	118	3.61%
1AX8	1074	146	3.54%

Table : Six proteins from the RCSB Protein Data Bank.²

²http://www.rcsb.org/

Table : Average (worst) results: 5,000 iterations, five random initializations.

Protein	Problem Size	Rel. Error (dB)	RMS Error	Max Error
1PTQ	81,406	-83.6 (-83.7)	0.02 (0.02)	0.08 (0.09)
1HOE	168,490	-72.7 (-69.3)	0.19 (0.26)	2.88 (5.49)
1LFB	205,120	-47.6 (-45.3)	3.24 (3.53)	21.68 (24.00)
1PHT	236,328	-60.5 (-58.1)	1.03 (1.18)	12.71 (13.89)
1POA	568,711	-49.3 (-48.1)	34.09 (34.32)	81.88 (87.60)
1AX8	576,201	-46.7 (-43.5)	9.69 (10.36)	58.55 (62.65)

• The reconstructed EDM is compared to the actual EDM using:

Relative error (decibels) =
$$10 \log_{10} \left(\frac{\|P_A x_n - P_B R_A x_n\|^2}{\|P_A x_n\|^2} \right).$$

• The reconstructed points in \mathbb{R}^3 are then compared using:

$$\mathsf{RMS Error} = \left(\sum_{k=1}^{m} \|z_k - z_k^{\mathsf{actual}}\|^2\right)^{1/2}, \ \mathsf{Max Error} = \max_{k=1,\dots,m} \|z_k - z_k^{\mathsf{actual}}\|,$$

which are computed up to translation, reflection and rotation.

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• Error metrics don't tell the whole story.

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Experiment 3: There are many projection methods, so why should we use the Douglas–Rachford method?



First 3,000 steps of the 1PTQ reconstruction

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Before reconstruction



Actual Structure



Douglas-Rachford method reconstruction:







500 steps, -25 dB $\,$

1,000 steps,-30 dB $\,$

2,000 steps, -51 dB

Method of alternating projections reconstruction:



500 steps,-22 dB



1,000 steps, -24 dB



2,000 steps, -25 dB

Recall from before:

Theorem (Basic behaviour of the Douglas–Rachford method)

Suppose C_1 , C_2 are closed convex subsets of a finite dimensional Hilbert space \mathcal{H} . For any $x_0 \in \mathcal{H}$, define $x_{n+1} = T_{C_1, C_2} x_n$. a) If $C_1 \cap C_2 \neq \emptyset$, then $x_n \to x$ such that $P_{C_1} x \in C_1 \cap C_2$. b) If $C_1 \cap C_2 = \emptyset$, then $||x_n|| \to +\infty$.

The corresponding theorem for alternating projections is:

Theorem (Basic behaviour of the method of alternating projections) Suppose C_1 , C_2 are closed convex subsets of a finite dimensional Hilbert space \mathcal{H} . For any $y_0 \in \mathcal{H}$, define $y_{n+1} = P_{C_2}P_{C_1}y_n$. If $C_1 \cap C_2 \neq \emptyset$, then $y_n \to y \in C_1 \cap C_2$. If $C_1 \cap C_2 = \emptyset$, then $||P_{C_1}y_n - y_n|| \to d(C_1, C_2)$.

Concluding Remarks and Future Work

- The Douglas-Rachford method can predict protein conformation using only short-range distances. It performs better than theory suggests.
- Local convergence results for this problem seems possible.
- Alternatively, can the method's behaviour be explained by a CAT(0) metric space interpretation?
- The Douglas-Rachford method is a general purpose algorithm. Can problem specific improvements of the method which exploit special structure present in our constraint sets be made?
- What other applications are fruitful? We are currently investigating an analogous problem of bulk structure determination arising in the context of ionic liquid chemistry.

Douglas–Rachford feasibility methods for matrix completion problems with F.J. Aragón Artacho & J.M. Borwein. *ANZIAM J.*, accepted 2014. arXiv:1312.7323 Many resources can be found at the companion website:

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When presented with a feasibility problem, it is well worth seeing if the Douglas–Rachford method can deal with it – the method is conceptually simple and easy to implement.

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